

Changes in CCCM SW and LW Irradiances with New Versions of Cloud Inputs and Algorithm Changes

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CCCM Flux Computations

- The CCCM flux algorithm takes cloud information from CALIPSO, CloudSat, and MODIS for better describing cloud vertical profiles and optical properties (Kato et al. 2011).
- RelB CCCM product was released in 2011, and development of RelD CCCM product is ongoing with new versions of CERES (Ed4), MODIS (Ed5), CALIPSO (V4), and CloudSat (R05).

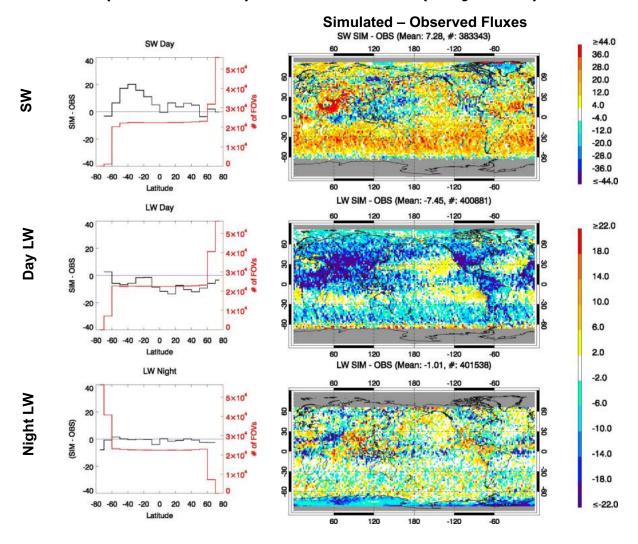
Objective

 We examine how much fluxes are changed from RelB to RelD, associated with implementing new datasets and algorithm improvements.

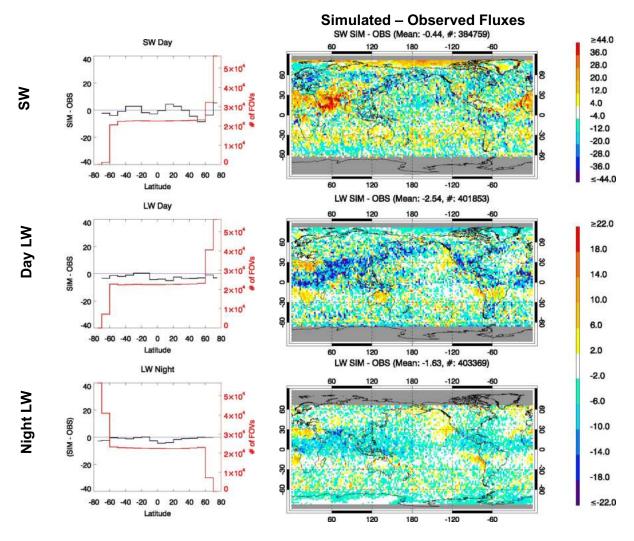
Input Parameters Used For RelB and RelD CCCM Flux Computations

	Release B (RelB)	Release D (ReID)
MODIS Clouds	Beta Edition 3 (Revised version of Ed2) (Smooth hexagonal single habit ice model)	Evolving Edition 5 (Two-habit ice model)
CALIPSO	V3	V4 Also water clouds below 4 km detected with non-single shots are excluded.
CloudSat 2B-CWC 2B-CLDCLASS	Release 4	Release 5 (Liquid 2B-CWC has been significantly changed but not the ice phase)
CloudSat 2C-ICE	Not used	Implemented, and used as a first choice
MATCH	Daily (MOD Collection 05)	Ed4 Hourly
Solar Constant	1365 W m ⁻² Fixed Value	SOLCE Database (~ 1361 W m ⁻² for July 2008)
Sea/Ice Albedo	Climatology	Pre-Processed Surface Albedo History (SAH) Map

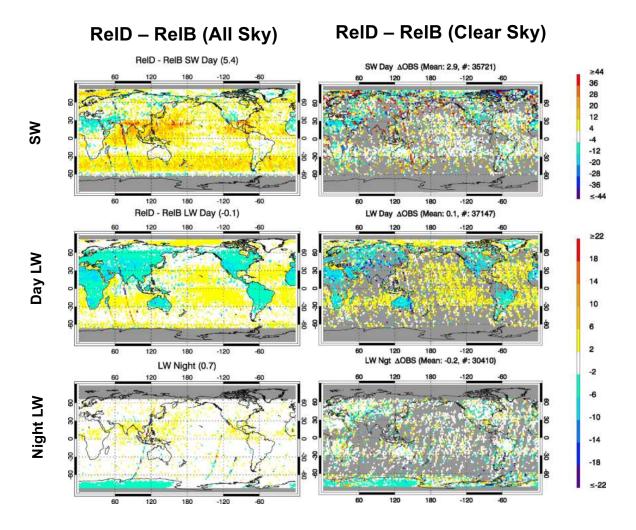
Simulated Flux Biases (= Sim – Obs) in CCCM RelB (July 2008)



Simulated Flux Biases in CCCM ReID (Ongoing Process) (July 2008)



CERES-Derived (Observed) Fluxes between RelB and RelD CCCM Products (July 2008)



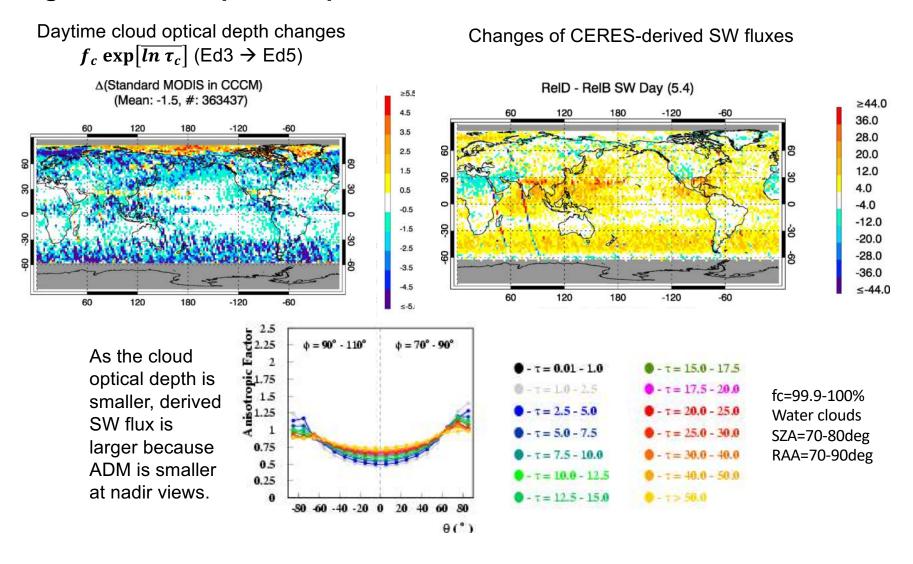
- Note that CERES fluxes in RelB and RelD CCCM products are different from those in SSF Ed2 or Ed4 products since Ed3 (revised Ed2) MODIS clouds were used for selecting Ed2 ADM types in RelB, and Ed5 MODIS clouds were used for selecting Ed4 ADM types in RelD.
- CCCM product only includes CERES footprints with nadir views, unlike SSF products.
- Observed (CERES-derived) SW fluxes are increased by 5.4 W m⁻² from RelB to RelD.

Changes of Simulation Biases from RelB to RelD for July 2008

W m ⁻²	RelB			ReID		
	Obs	Sim	Sim – Obs (Mean±RMSD)	Obs	Sim	Sim – Obs (Mean±RMSD)
SW	222.2	229.5	+7.28 ± 46.71	227.6 (+5.4)	227.2 (–2.3)	-0.44 ± 35.97 (+7.7)
Day LW	251.6	244.1	-7.45 ± 20.07	251.5 (–0.1)	249.0 (+4.9)	-2.54 ± 14.87 (-4.9)
Night LW	242.0	241.0	-1.01 ± 19.92	242.7 (+0.7)	241.1 (+0.1)	-1.63 ± 8.94 (-0.6)

- Both mean biases and RMSDs are improved in ReID, compared to ReIB.
- From RelB to RelD, SW observed fluxes are increased by 5.4 W m⁻², and this explains 70% of changes of SW flux biases (= simulated observed fluxes). In addition, SW fluxes are decreased by 2.3 W m⁻², resulting in decrease of SW biases by 7.7 W m⁻².
- Simulated daytime LW fluxes are increased by 4.9 W m⁻².

Changes in Cloud Optical Depths and CERES-Derived SW fluxes from RelB to RelD



Causes of Simulated Flux Changes between RelB and RelD CCCM

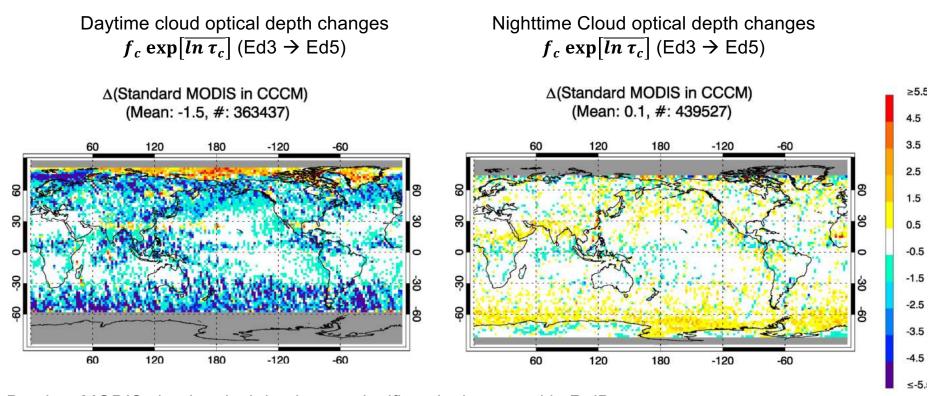
Cloud Input Changes

- 1) Changes in MODIS cloud optical depths (and ice scattering model)
- 2) Reduction of CC cloud covers due to exclusion of CALIPSO water clouds detected with non-single shots

Cloud Algorithm Changes

- 1) New nighttime IR constraining method of merged cloud profiles
- 2) Different cloud phase assignment using temperature, CALIPSO phase, 2C-ICE

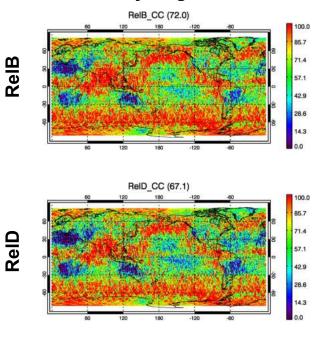
Changes in MODIS Cloud Optical Depths from RelB to RelD

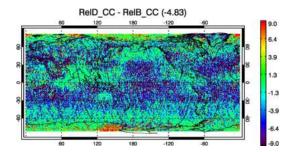


• Daytime MODIS cloud optical depths are significantly decreased in ReID.

Changes in CALIPSO-CloudSat (CC) Cloud Area

Day+Night





ReID - ReIB

- For flux computations, we determine whether the area is clear or not based on CALIPSO-CloudSat detections.
- In ReID, water clouds below 4 km detected with nonsingle CALIPSO lidar beam are screened out. This is because water particles generate strong lidar signals and affect surrounding pixels if spatial averaging is taken, causing over-detections of water clouds.
- By excluding water clouds with non-single shots, CC cloud areas are largely reduced over broken cloud regions, located between overcast and clear regions, which decreases SW fluxes and increase LW fluxes.

(July 2008)

Step1: Determine cloud phase for each vertical grid bin Using **Temperature and CALIPSO Phase**

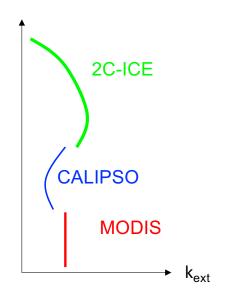
CC cloud boundary

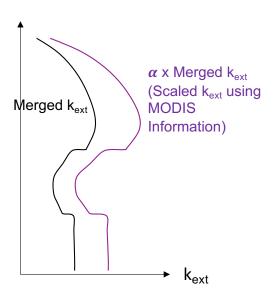
Ice Phase -20°C **Choice Priority** 1. Ice Phase if 2C-ICE is Available 2. CALIPSO Phase 3. MODIS Phase 0°C Liquid Phase

Step 2: Merging Cloud Profiles Using CALIPSO, CloudSat, and **MODIS**

<u>lce</u>	<u>Phase</u>	<u>Wa</u>	Water Phase		
1.	2C-ICE	1.	CALIPSO		
2.	CALIPSO	2.	CloudSat		
3.	CloudSat	3.	MODIS		
4.	MODIS				

Step 3: Normalizing the merged cloud extinction profile (or obtaining a scaling factor a) with **MODIS** information





Normalizing Merged Cloud Extinction Profiles with MODIS Information [A scaling Factor (α) applied to the merged cloud profile]

When MODIS cloud optical depth is derived from visible channels (SZA ≤ 82°) (Kato et al., 2011)

$$\tau_{M}(1-g(r_{M})) = \alpha \sum_{i=1}^{n} k_{CCM}(i) \Delta z_{i} \left(1-g(r_{CCM}(i))\right)$$

MODIS Scaled Cloud Optical Depth

 α is a scaling factor to reproduce MODIS-equivalent scaled optical depth from the merged extinction profile ($k_{CCM}(i)$).

This normalization works well when the MODIS cloud optical depth is retrieved from VIS channel.

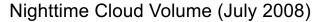
When MODIS cloud optical depth is derived from infrared channels (SZA > 82°) – Added in RelD

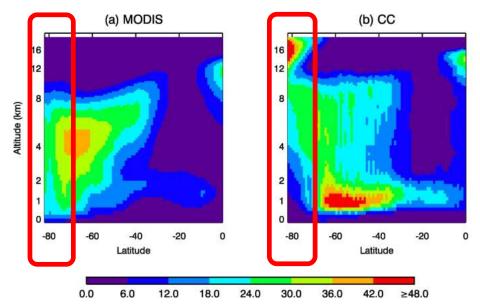
$$\varepsilon_{11}B(T_{skin})\exp(-\tau_M) + (1-\exp(-\tau_M))B(T_{eff,MODIS})$$
 "MODIS-estimated IR emission"

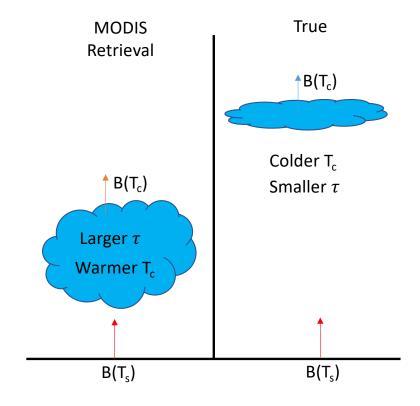
$$= \varepsilon_{11} B(T_{skin}) \exp\left(-\alpha \sum_{i=1}^{n} k_{CCM}(i) \Delta z_i\right) + \sum_{i=1}^{n} \left\{ (1 - \exp(-\alpha k_{CCM}(i) \Delta z_i)) B(T_i) \exp\left[-\sum_{j=i+1}^{n} \alpha k_{CCM}(i) \Delta z_i\right] \right\}$$

 α is a scaling factor to reproduce MODIS-equivalent IR emission from the merged extinction profile ($k_{CCM}(i)$).

Nighttime MODIS Algorithm over the Antarctica





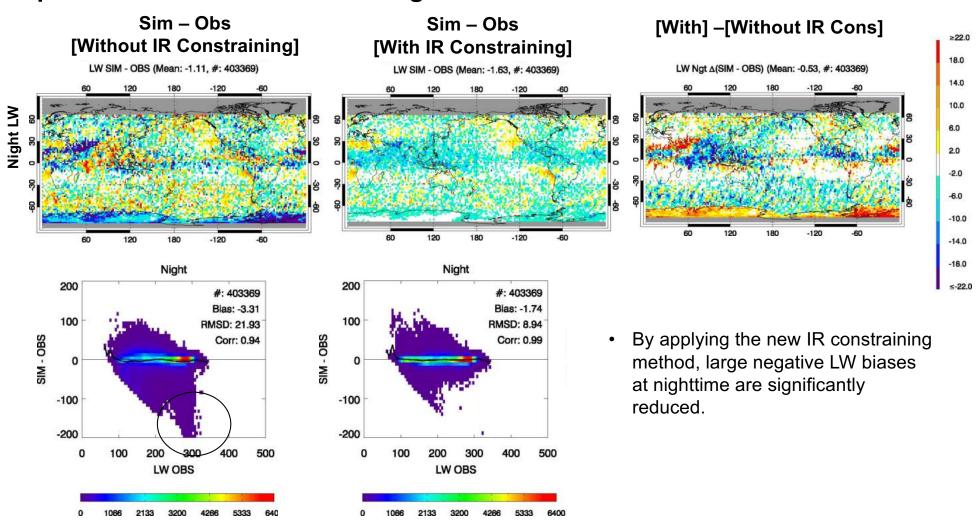


 Over the Antarctica, nighttime MODIS algorithm often detects lower clouds (0-8 km) than CC (> 12 km).

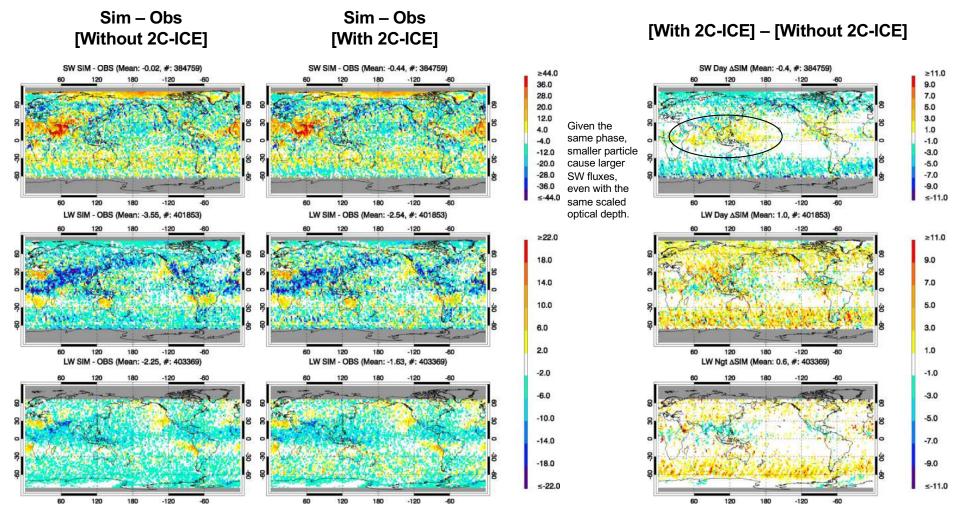
$$R_{IR} = \varepsilon_s B(T_s) \exp(-\tau_c) + B(T_c)(1 - \exp(-\tau_c))$$
Warm biased Positively biased

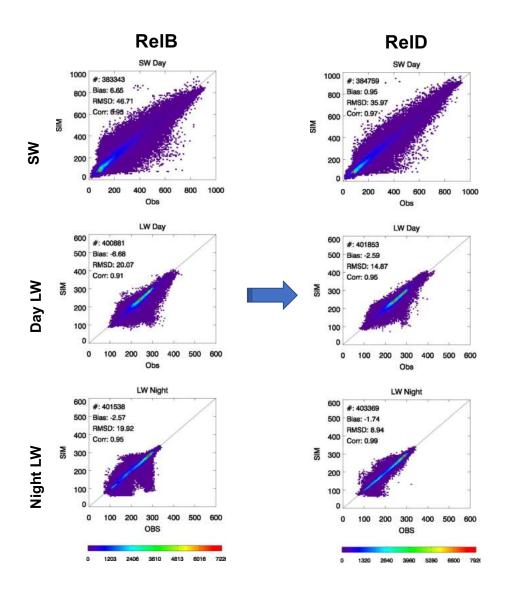
• In the IR cloud algorithm, cloud optical depth and cloud effective temperature are balanced to reproduce IR channel radiance. Therefore, low-biased cloud height (or warm-biased cloud effective temperature; T_c) means overestimated cloud optical depth.

Impact of The New IR Constraining Method for SZA > 82°



Impact of Brining 2C-ICE in CCCM Flux Algorithm (With 2CICE – Without 2CICE)





Summary

- better agreement with CERES-derived fluxes.

 Specifically, the positive SW biases shown in RelB are largely decreased in RelD. This is because

 1) CERES-derived SW fluxes are increased by 5.4 W m⁻², and 2) simulated SW fluxes are decreased by 2.3 W m⁻² in RelD.
- Daytime simulated LW fluxes are increased by 5 W m⁻² and it results in better agreement with observations.
- New IR constraining method improves nighttime negative LW biases over the Antarctica.